

LGXS05

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS05

Model	Lead	Side cover	Stroke
	20: 20 mm 10: 10 mm 5: 5 mm	No entry: Standard W: With T-groove (both sides) R: With T-groove (right side) L: With T-groove (left side)	50 to 800 (50 mm pitch)

[Caution]

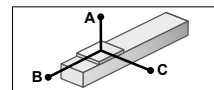
This system is provided as mechanical actuator unit and not including any adopters or electric components. Motor, driver and other components required for installation are the user's responsibility. Refer to user's manual for installation details. Refer to your motor manual for tuning or adjustment. Vibration or resonance from actuator will affect service life of actuator. The product performance may not be satisfied depending on the compatible motor. The bending unit cannot be used for the high agility mode.

Specifications

Applicable motor	50 W		
Repeatability ^{Note 1}	+/- 0.005 mm		
Deceleration mechanism	Ground ball screw ϕ 12 (C5 class)		
Stroke	50 mm to 800 mm (50 mm pitch)		
Maximum speed ^{Note 2} (or equivalent)	1333 mm/sec	666 mm/sec	333 mm/sec
Ball screw lead	20 mm	10 mm	5 mm
Maximum payload ^{Note 3} (or equivalent)	Horizontal 5 kg	8 kg	13 kg
	Vertical 2 kg	4 kg	8 kg
Rated thrust ^{Note 3} (or equivalent)	41 N	69 N	138 N
Maximum dimensions of cross section of main unit	W 48 mm x H 65 mm		
Overall length	ST + 131.5 mm		
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent		
Intake air ^{Note 5}	30 N ℓ /min to 100 N ℓ /min		
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)		

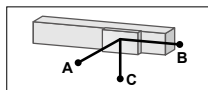
- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed. If the effective stroke exceeds 600 mm, the ball screw may resonate. (Critical speed)
 At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.115 for acceleration/deceleration and inertia moment.

Allowable overhang ^{Note}



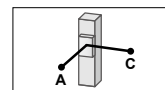
LGXS05-20

Horizontal installation (Unit: mm)	A			B			C		
2kg	898	269	350						
5kg	583	112	159						



Wall installation (Unit: mm)

	A			B			C		
2kg	323	234	809						
5kg	119	76	427						



Vertical installation (Unit: mm)

	A		C	
1kg	452	452		
2kg	217	217		

LGXS05-10

Horizontal installation (Unit: mm)	A			B			C		
2kg	2505	382	625						
5kg	1366	149	246						
8kg	1036	90	150						

Wall installation (Unit: mm)	A			B			C		
2kg	585	346	2386						
5kg	195	113	1164						
8kg	95	54	745						

Vertical installation (Unit: mm)	A		C	
1kg	732	732		
2kg	351	351		
4kg	160	160		

LGXS05-5

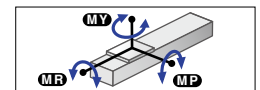
Horizontal installation (Unit: mm)	A			B			C		
3kg	4604	281	497						
8kg	2197	101	179						
13kg	1593	59	105						

Wall installation (Unit: mm)	A			B			C		
3kg	439	245	4371						
8kg	117	65	1812						
13kg	42	24	1000						

Vertical installation (Unit: mm)	A		C	
4kg	183	183		
6kg	111	111		
8kg	75	75		

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Static loading moment



(Unit: N·m)		
MY	MP	MR
24	27	23

Adaptable Servo Motor

Specification	Flange size <input type="checkbox"/> 40
	Wattage 50 W

Manufacturer	Model
Yaskawa Electric Corp.	SGMJV-A5 SGM7J-A5
Keyence Corp.	SV- <input type="checkbox"/> 005 SV2- <input type="checkbox"/> 005
Mitsubishi Electric Corp.	HF-KP053 ^{Note} HG-KR053 ^{Note} HK-KT053 ^{Note}
Omron Electronics	R88M-K05030 R88M-1M05030 ^{Note}
Panasonic Corp.	MHMF5A

Conversion adapter product model	Shim plate part number
GX-BEND-40	KES-M2295-00

Note. To combine with the conversion adapter <GX-BEND-40>, the shim plate (t1) is necessary.

When used with high acceleration or deceleration (High agility mode)

Specifications

Stroke	50 mm to 550 mm (50 mm pitch)		
Ball screw lead	20 mm	10 mm	5 mm
Maximum payload	2 kg	3 kg	-
Maximum acceleration	Horizontal 11.77 m/s ² (1.2 G)	11.77 m/s ² (1.2 G)	-
Maximum payload	1 kg	2 kg	3 kg
Maximum acceleration	Vertical 11.77 m/s ² (1.2 G)	11.77 m/s ² (1.2 G)	7.17 m/s ² (0.7 G)

Allowable overhang ^{Note}

LGXS05-20

Horizontal installation (Unit: mm)	A			B			C		
1kg	498	324	323						
2kg	230	157	150						

Wall installation (Unit: mm)	A			B			C		
1kg	297	288	468						
2kg	123	120	199						

Vertical installation (Unit: mm)	A		C	
1kg	223	223		

LGXS05-10

Horizontal installation (Unit: mm)	A			B			C		
1kg	1159	460	645						
3kg	381	148	206						

Wall installation (Unit: mm)	A			B			C		
1kg	606	424	1129						
3kg	163	112	346						

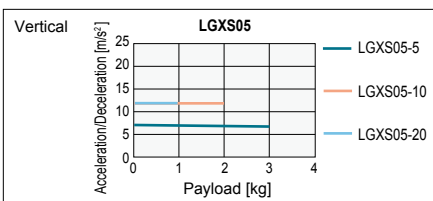
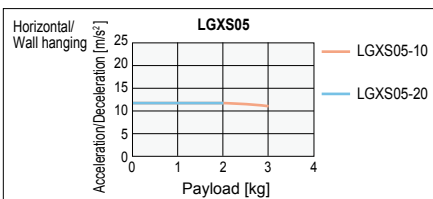
Vertical installation (Unit: mm)	A		C	
1kg	396	396		
2kg	182	182		

LGXS05-5

Vertical installation (Unit: mm)	A		C	
1kg	478	478		
3kg	138	138		

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 550 mm stroke models.

Payload - Acceleration / Deceleration Graph (Estimate)



Effective stroke and maximum speed during high acceleration or deceleration

Effective stroke	50	100	150	200	250	300	350	400	450	500	550
Maximum speed (mm/sec)	Lead 20	1333									
	Lead 10	666									
	Lead 5	333									

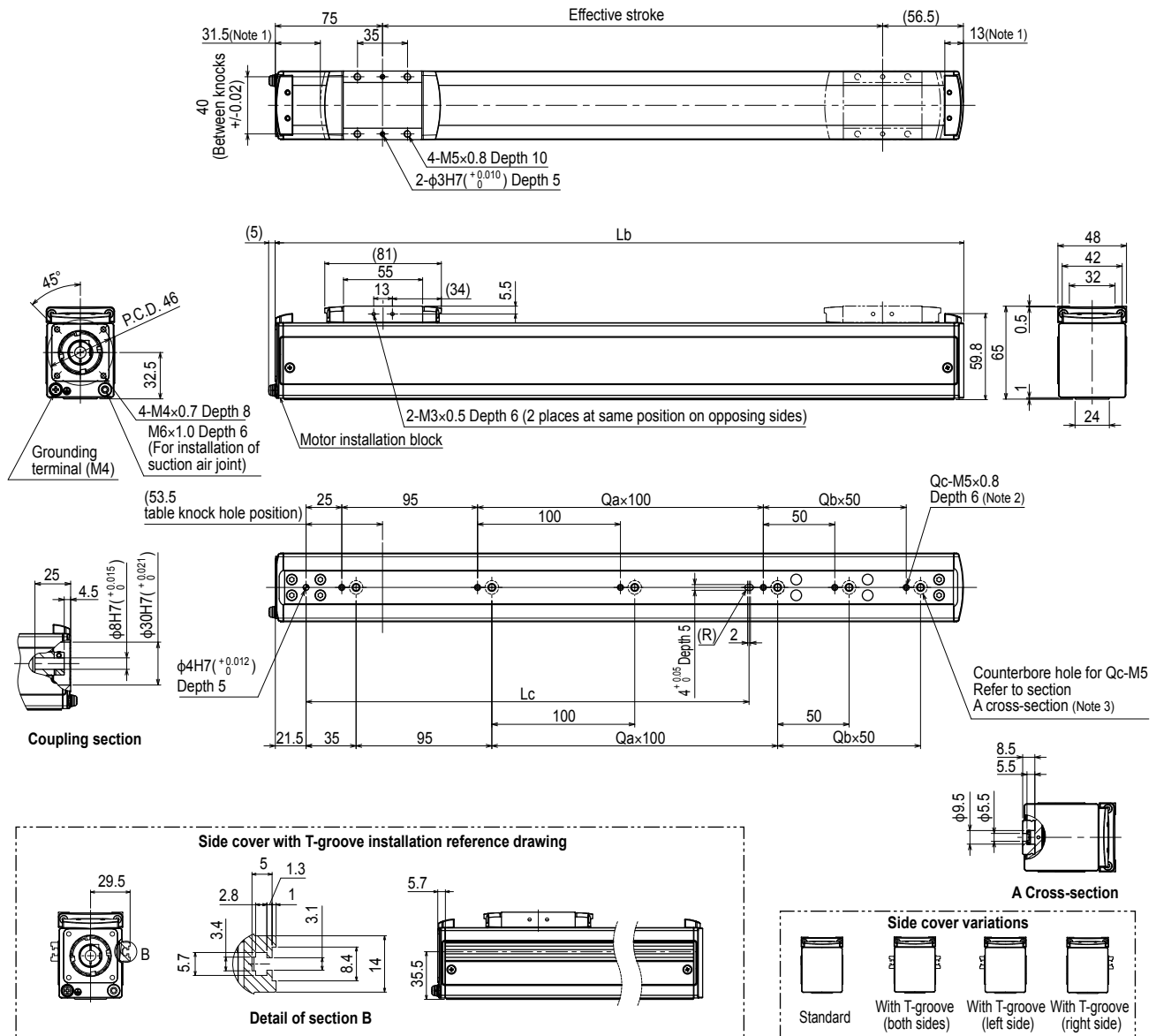
Note. The bending unit cannot be used for the high agility mode.
 Note. The high agility mode is used in an effective stroke range of 50 to 550 (50 mm pitch).
 Note. There is no critical speed setting. The maximum speed can be set for a selectable stroke.
 The speed may not reach the maximum speed if the movement distance is short or depending on the operating conditions.
 Note. See P.116 for acceleration/deceleration and inertia moment.

Access the website below.



▶ The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS05



- Note 1. Stop positions are determined by the mechanical stoppers at both ends.
- Note 2. When using the tap holes to mount the body, remove the set screws first.
- Note 3. When using the counterbore holes (section A cross section) to mount the body, remove the cap from the inner side and then fix. The length under head of the hex socket head bolts (M5 × 0.8) used must be 15 mm or less.
- Note 4. Side cover with T-groove is used to install the sensor.
- Note 5. Grease gun nozzle (recommended) (see P.143 for detail)

Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	
Lb	181.5	231.5	281.5	331.5	381.5	431.5	481.5	531.5	581.5	631.5	681.5	731.5	781.5	831.5	881.5	931.5	
Lc	110	110	110	110	310	310	310	310	310	310	610	610	610	610	610	610	
Qa	0	0	0	0	2	2	2	2	2	2	5	5	5	5	5	5	
Qb	0	1	2	3	0	1	2	3	4	5	0	1	2	3	4	5	
Qc	2	3	4	5	4	5	6	7	8	9	7	8	9	10	11	12	
Weight (kg)	1.2	1.4	1.5	1.7	1.9	2.0	2.2	2.3	2.5	2.6	2.8	2.9	3.1	3.2	3.4	3.5	
Maximum speed (mm/sec)	Lead 20												1333	1066	933	800	666
	Lead 10												666	532	466	400	333
	Lead 5												333	266	233	200	166
	Speed setting												-	80%	70%	60%	50%

Features

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Acceleration/Deceleration

Inertia Moment

Option

Single axis sensor positioner

EP-01

LGXS05L

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS05L

Model	Lead	Side cover	Stroke
	20: 20 mm 10: 10 mm 5: 5 mm	No entry: Standard W: With T-groove (both sides) R: With T-groove (right side) L: With T-groove (left side)	50 to 800 (50 mm pitch)

[Caution]

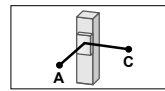
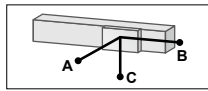
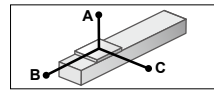
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Specifications

Applicable motor	100 W	
Repeatability ^{Note 1}	+/-0.005 mm	
Deceleration mechanism	Ground ball screw ϕ 12 (C5 class)	
Stroke	50 mm to 800 mm (50 mm pitch)	
Maximum speed ^{Note 2} (or equivalent)	1333 mm/sec 666 mm/sec 333 mm/sec	
Ball screw lead	20 mm 10 mm 5 mm	
Maximum payload ^{Note 3} (or equivalent)	Horizontal	12 kg 24 kg 32 kg
	Vertical	3 kg 6 kg 12 kg
Rated thrust ^{Note 3} (or equivalent)	Horizontal	84 N 169 N 339 N
	Vertical	3 kg 6 kg 12 kg
Maximum dimensions of cross section of main unit	W 48 mm x H 65 mm	
Overall length	ST + 161.5 mm	
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent	
Intake air ^{Note 5}	30 N ℓ /min to 100 N ℓ /min	
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)	

- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed. If the effective stroke exceeds 600 mm, the ball screw may resonate. (Critical speed) At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.117 for acceleration/deceleration and inertia moment.

Allowable overhang ^{Note}



LGXS05L-20

Horizontal installation (Unit: mm)	A B C		
3kg	1755	559	426
8kg	737	200	153
12kg	608	133	104

Wall installation (Unit: mm)	A B C		
3kg	396	486	1594
8kg	106	128	525
12kg	52	61	329

Vertical installation (Unit: mm)	A C	
1kg	1486	1486
2kg	730	730
3kg	478	478

LGXS05L-10

Horizontal installation (Unit: mm)	A B C		
6kg	2416	389	333
12kg	1397	187	161
24kg	875	87	74

Wall installation (Unit: mm)	A B C		
6kg	277	316	2192
12kg	101	115	1084
24kg	12	14	276

Vertical installation (Unit: mm)	A C	
4kg	555	555
6kg	360	360

LGXS05L-5

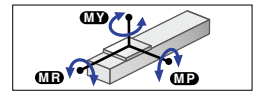
Horizontal installation (Unit: mm)	A B C		
10kg	3127	254	225
20kg	1841	120	106
32kg	1554	70	62

Wall installation (Unit: mm)	A B C		
10kg	162	181	2800
20kg	42	47	1273
32kg	0	0	0

Vertical installation (Unit: mm)	A C	
5kg	501	501
10kg	235	235
12kg	190	190

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Static loading moment



(Unit: N·m)		
MY	MP	MR
72	72	64

Adaptable Servo Motor

Specification	Flange size <input type="checkbox"/> 40
	Wattage 100 W
Manufacturer	Model
Yaskawa Electric Corp.	SGMJV-01 SGM7J-01
Keyence Corp.	SV- <input type="checkbox"/> 010 SV2- <input type="checkbox"/> 010
Mitsubishi Electric Corp.	HF-KP13 ^{Note} HG-KR13 ^{Note} HK-KT13 ^{Note}
Omron Electronics	R88M-K10030 R88M-1M10030 ^{Note}
Panasonic Corp.	MHMF01

Conversion adapter product model	Shim plate part number
GX-BEND-40	KES-M2295-00

Note. To combine with the conversion adapter <GX-BEND-40>, the shim plate (t1) is necessary.

When used with high acceleration or deceleration (High agility mode)

Specifications

Stroke	50 mm to 550 mm (50 mm pitch)		
Ball screw lead	20 mm	10 mm	5 mm
Maximum payload	Horizontal	5 kg	10 kg
	Vertical	1 kg	2 kg
Maximum acceleration	Horizontal	14.72 m/s ² (1.5 G)	14.72 m/s ² (1.5 G)
	Vertical	14.72 m/s ² (1.5 G)	12.68 m/s ² (1.3 G)
Maximum acceleration	Horizontal	6.65 m/s ² (0.7 G)	6.65 m/s ² (0.7 G)
	Vertical	14.72 m/s ² (1.5 G)	12.68 m/s ² (1.3 G)

Allowable overhang ^{Note}

LGXS05L-20

Horizontal installation (Unit: mm)	A B C		
2kg	675	501	332
5kg	330	191	131

Wall installation (Unit: mm)	A B C		
2kg	294	428	626
5kg	87	118	251

Vertical installation (Unit: mm)	A C	
1kg	728	728

LGXS05L-10

Horizontal installation (Unit: mm)	A B C		
3kg	1208	469	385
6kg	665	227	188
10kg	441	130	108

Wall installation (Unit: mm)	A B C		
3kg	331	396	1144
6kg	131	155	580
10kg	49	58	315

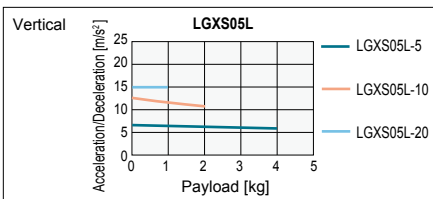
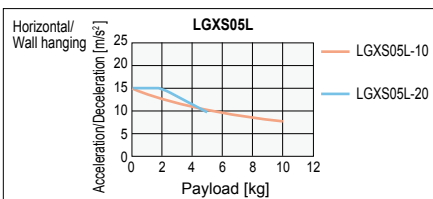
Vertical installation (Unit: mm)	A C	
1kg	1298	1298
2kg	636	636

LGXS05L-5

Vertical installation (Unit: mm)	A C	
1kg	1555	1555
2kg	762	762
4kg	365	365

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 550 mm stroke models.

Payload - Acceleration / Deceleration Graph (Estimate)



Effective stroke and maximum speed during high acceleration or deceleration

Effective stroke	50	100	150	200	250	300	350	400	450	500	550
Maximum speed (mm/sec)	Lead 20	1333									
	Lead 10	666									
	Lead 5	333									

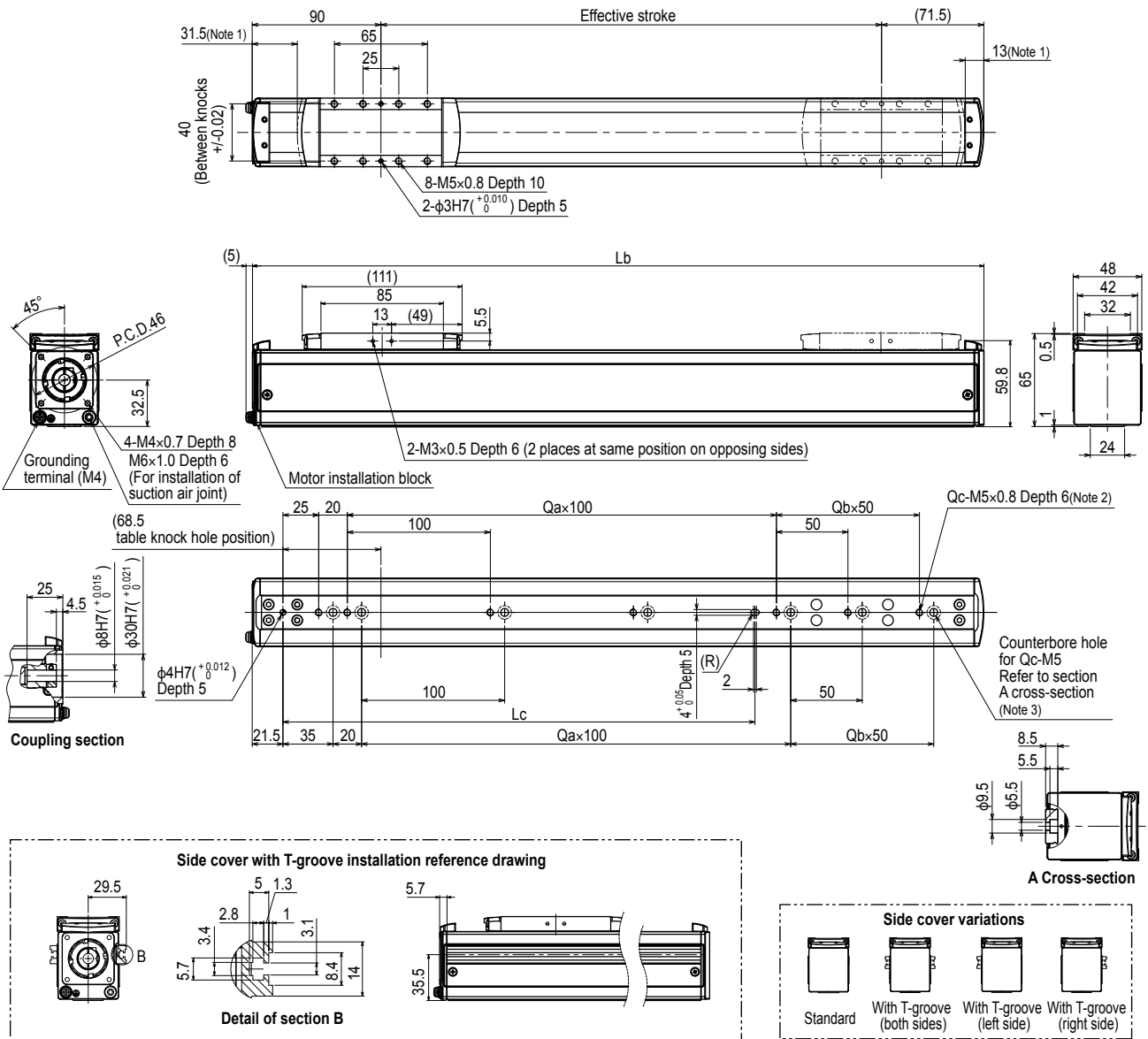
Note. The bending unit cannot be used for the high agility mode.
 Note. The high agility mode is used in an effective stroke range of 50 to 550 (50 mm pitch).
 Note. There is no critical speed setting. The maximum speed can be set for a selectable stroke.
 The speed may not reach the maximum speed if the movement distance is short or depending on the operating conditions.
 Note. See P.118 for acceleration/deceleration and inertia moment.

Access the website below.



▶ The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS05L



- Note 1. Stop positions are determined by the mechanical stoppers at both ends.
- Note 2. When using the tap holes to mount the body, remove the set screws first.
- Note 3. When using the counterbore holes (section A cross section) to mount the body, remove the cap from the inner side and then fix. The length under head of the hex socket head bolts (M5 × 0.8) used must be 15 mm or less.
- Note 4. Side cover with T-groove is used to install the sensor.
- Note 5. Grease gun nozzle (recommended) (see P.143 for detail)

Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	
Lb	211.5	261.5	311.5	361.5	411.5	461.5	511.5	561.5	611.5	661.5	711.5	761.5	811.5	861.5	911.5	961.5	
Lc	130	130	130	130	330	330	330	330	330	330	630	630	630	630	630	630	
Qa	1	1	1	1	3	3	3	3	3	3	6	6	6	6	6	6	
Qb	0	1	2	3	0	1	2	3	4	5	0	1	2	3	4	5	
Qc	3	4	5	6	5	6	7	8	9	10	8	9	10	11	12	13	
Weight (kg)	1.4	1.5	1.7	1.8	2.0	2.2	2.3	2.5	2.6	2.8	2.9	3.1	3.2	3.4	3.5	3.7	
Maximum speed (mm/sec)	Lead 20												1333	1066	933	800	666
	Lead 10												666	532	466	400	333
	Lead 5												333	266	233	200	166
	Speed setting												-	80%	70%	60%	50%

Features

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Acceleration/Deceleration Inertia Moment

Option

Single axis force positioner EP-01

LGXS07

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS07

Model	Lead	Side cover	Stroke
	30: 30 mm 20: 20 mm 10: 10 mm 5: 5 mm	No entry: Standard W: With T-groove (both sides) R: With T-groove (right side) L: With T-groove (left side)	50 to 1100 (50 mm pitch)

[Caution]

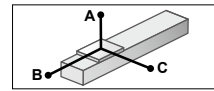
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Specifications

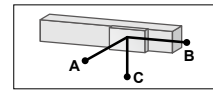
Applicable motor	100 W	
Repeatability ^{Note 1}	+/-0.005 mm	
Deceleration mechanism	Ground ball screw ϕ 15 (C5 class)	
Stroke	50 mm to 1100 mm (50 mm pitch)	
Maximum speed ^{Note 2} (or equivalent)	1800 mm/sec 1200 mm/sec 600 mm/sec 300 mm/sec	
Ball screw lead	30 mm 20 mm 10 mm 5 mm	
Maximum payload ^{Note 3} (or equivalent)	Horizontal	10 kg 25 kg 45 kg 85 kg
	Vertical	2 kg 4 kg 8 kg 16 kg
Rated thrust ^{Note 3} (or equivalent)	Horizontal	56 N 84 N 169 N 339 N
	Vertical	56 N 84 N 169 N 339 N
Maximum dimensions of cross section of main unit	W 70 mm x H 76.5 mm	
Overall length	ST + 202 mm	
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent	
Intake air ^{Note 5}	30 N ℓ /min to 115 N ℓ /min	
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)	

- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed.
 If the effective stroke exceeds 700 mm, the ball screw may resonate. (Critical speed)
 At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.119 for acceleration/deceleration and inertia moment.

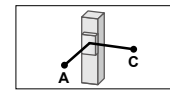
Allowable overhang ^{Note}



LGXS07-30			
Horizontal installation (Unit: mm)	A	B	C
2kg	3078	1509	1221
6kg	1191	501	418
10kg	957	317	282

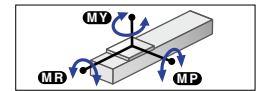


Wall installation (Unit: mm)			
A	B	C	
2kg	1237	1442	2975
6kg	393	435	1062
10kg	244	251	793



Vertical installation (Unit: mm)		
A	C	
1kg	2335	2335
2kg	1158	1158

Static loading moment



(Unit: N·m)		
MY	MP	MR
138	121	121

Adaptable Servo Motor

Specification	Flange size <input type="checkbox"/> 40 Wattage 100 W
Manufacturer	Model
Yaskawa Electric Corp.	SGMJV-01 SGM7J-01
Keyence Corp.	SV- <input type="checkbox"/> 010 SV2- <input type="checkbox"/> 010
Mitsubishi Electric Corp.	HF-KP13 ^{Note} HG-KR13 ^{Note} HK-KT13 ^{Note}
Omron Electronics	R88M-K10030 R88M-1M10030 ^{Note}
Panasonic Corp.	MHMF01
Conversion adapter product model	Shim plate part number
GX-BEND-40	KES-M2295-00

Note. To combine with the conversion adapter <GX-BEND-40>, the shim plate (t1) is necessary.

When used with high acceleration or deceleration (High agility mode)

Specifications

Stroke	50 mm to 650 mm (50 mm pitch)			
Ball screw lead	30 mm	20 mm	10 mm	5 mm
Maximum payload	Horizontal	5 kg	10 kg	20 kg
	Vertical	1 kg	2 kg	4 kg
Maximum acceleration	Horizontal	14.72 m/s ² (1.5 G)	14.72 m/s ² (1.5 G)	9.64 m/s ² (1 G)
	Vertical	14.72 m/s ² (1.5 G)	14.72 m/s ² (1.5 G)	8.44 m/s ² (0.9 G)

Allowable overhang ^{Note}

LGXS07-30			
Horizontal installation (Unit: mm)	A	B	C
2kg	1020	897	608
5kg	461	346	245

Wall installation (Unit: mm)			
A	B	C	
2kg	579	830	976
5kg	208	279	401

Vertical installation (Unit: mm)		
A	C	
1kg	1165	1165

LGXS07-5		
Vertical installation (Unit: mm)	A	C
3kg	1093	1093
5kg	639	639
8kg	384	384

LGXS07-20			
Horizontal installation (Unit: mm)	A	B	C
3kg	1224	758	640
6kg	684	369	321
10kg	459	214	190

Wall installation (Unit: mm)			
A	B	C	
3kg	600	692	1175
6kg	274	303	621
10kg	138	147	376

Vertical installation (Unit: mm)		
A	C	
1kg	1793	1793
2kg	891	891

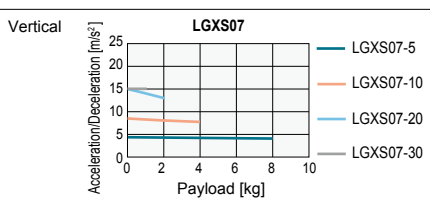
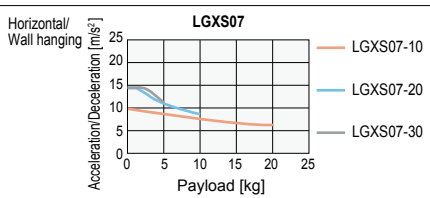
LGXS07-10			
Horizontal installation (Unit: mm)	A	B	C
5kg	2208	622	665
12kg	991	249	266
20kg	637	142	152

Wall installation (Unit: mm)			
A	B	C	
5kg	603	556	2129
12kg	200	182	890
20kg	83	75	497

Vertical installation (Unit: mm)		
A	C	
1kg	3012	3012
2kg	1487	1487
4kg	725	725

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Payload - Acceleration / Deceleration Graph (Estimate)



Effective stroke and maximum speed during high acceleration or deceleration

Effective stroke	50 100 150 200 250 300 350 400 450 500 550 600 650											
	Lead 30	1800										
Maximum speed (mm/sec)	Lead 20	1200										
	Lead 10	600										
	Lead 5	300										

Note. The bending unit cannot be used for the high agility mode.
 Note. The high agility mode is used in an effective stroke range of 50 to 650 (50 mm pitch).
 Note. There is no critical speed setting. The maximum speed can be set for a selectable stroke.
 The speed may not reach the maximum speed if the movement distance is short or depending on the operating conditions.
 Note. See P.121 for acceleration/deceleration and inertia moment.

Access the website below.



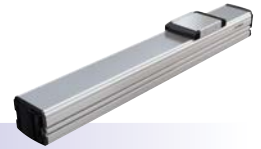
▶ The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS10

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS10

Model	Lead	Motor specification	Stroke
	30: 30 mm 20: 20 mm 10: 10 mm 5: 5 mm	No entry: Standard P: P specification (see below)	100 to 1250 (50 mm pitch)

[Caution]

This system is provided as mechanical actuator unit and not including any adapters or electric components. Motor, driver and other components required for installation are the user's responsibility. Refer to user's manual for installation details. Refer to your motor manual for tuning or adjustment. Vibration or resonance from actuator will affect service life of actuator. The product performance may not be satisfied depending on the compatible motor. The bending unit cannot be used for the high agility mode.

Specifications

Applicable motor	200 W			
Repeatability ^{Note 1}	±0.005 mm			
Deceleration mechanism	Ground ball screw φ 15 (C5 class)			
Stroke	100 mm to 1250 mm (50 mm pitch)			
Maximum speed ^{Note 2} (or equivalent)	1800 mm/sec	1200 mm/sec	600 mm/sec	300 mm/sec
Ball screw lead	30 mm	20 mm	10 mm	5 mm
Maximum payload ^{Note 3} (or equivalent)	Horizontal	25 kg	40 kg	80 kg
	Vertical	4 kg	8 kg	20 kg
Rated thrust ^{Note 3} (or equivalent)	113 N	170 N	341 N	683 N
Maximum dimensions of cross section of main unit	W 100 mm × H 99.5 mm			
Overall length	ST + 175.5 mm			
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent			
Intake air ^{Note 5}	30 Nℓ/min to 90 Nℓ/min			
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)			

- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed.
 If the effective stroke exceeds 700 mm, the ball screw may resonate. (Critical speed)
 At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.122 for acceleration/deceleration and inertia moment.

Allowable overhang ^{Note}

LGXS10-30	Wall installation (Unit: mm)	Vertical installation (Unit: mm)
Horizontal installation (Unit: mm)	A B C	A C
10kg 878 537 292	10kg 271 473 803	1kg 4135 4135
20kg 609 256 146	20kg 118 192 481	4kg 985 985
25kg 608 211 124	25kg 93 147 454	
LGXS10-20	Wall installation (Unit: mm)	Vertical installation (Unit: mm)
Horizontal installation (Unit: mm)	A B C	A C
15kg 1269 451 282	15kg 252 387 1159	3kg 2062 2062
25kg 754 253 158	25kg 123 189 629	6kg 1012 1012
40kg 466 142 88	40kg 51 78 311	8kg 750 750
LGXS10-10	Wall installation (Unit: mm)	Vertical installation (Unit: mm)
Horizontal installation (Unit: mm)	A B C	A C
30kg 1794 298 203	30kg 162 234 1623	5kg 1926 1926
50kg 1358 162 111	50kg 68 98 1060	10kg 931 931
80kg 1266 86 59	80kg 16 22 552	20kg 434 434
LGXS10-5	Wall installation (Unit: mm)	Vertical installation (Unit: mm)
Horizontal installation (Unit: mm)	A B C	A C
30kg 5605 321 225	30kg 181 258 5195	10kg 1018 1018
50kg 3694 177 124	50kg 79 113 3111	20kg 477 477
80kg 2619 95 67	80kg 22 31 1557	30kg 296 296
100kg 2224 68 48	100kg 0 0 0	

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Static loading moment

	(Unit: N·m)		
MY	MP	MR	
274	274	241	

Adaptable Servo Motor

Specification	Flange size	□60
	Wattage	200 W
Motor specification	Manufacturer	Model
No entry	Yaskawa Electric Corp.	SGMJV-02 SGMJ-02
	Keyence Corp.	SV-□020 SV2-□020
	Mitsubishi Electric Corp.	HF-KP23 HG-KR23 ^{Note 1} HK-KT23 ^{Note 1}
	Omron Electronics	R88M-K20030 R88M-1M20030
P	Panasonic Corp.	MSMD02 MSMF02 MHMF02
Conversion adapter product model	Shim plate part number	
GX-BEND-60 ^{Note 2}	KEV-M2295-00	

Note 1. To combine with the conversion adapter <GX-BEND-60>, the shim plate (t1) is necessary.
 Note 2. For the specifications P, the bending unit cannot be used.

When used with high acceleration or deceleration (High agility mode)

Specifications

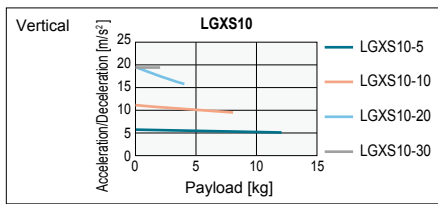
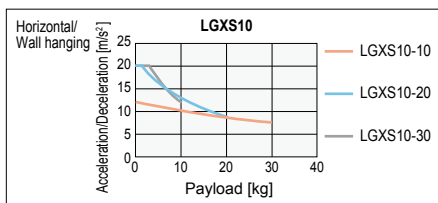
Stroke	100 mm to 650 mm (50 mm pitch)			
Ball screw lead	30 mm	20 mm	10 mm	5 mm
Maximum payload	Horizontal	10 kg	20 kg	30 kg
	Vertical	2 kg	4 kg	8 kg
Maximum acceleration	Horizontal	19.62 m/s ² (2 G)	19.62 m/s ² (2 G)	11.71 m/s ² (1.2 G)
	Vertical	19.62 m/s ² (2 G)	19.62 m/s ² (2 G)	10.84 m/s ² (1.1 G)

Allowable overhang ^{Note}

LGXS10-30	Wall installation (Unit: mm)	Vertical installation (Unit: mm)
Horizontal installation (Unit: mm)	A B C	A C
3kg 1041 1117 541	3kg 521 1046 1009	1kg 2054 2054
6kg 581 534 266	6kg 241 466 539	2kg 994 994
10kg 384 300 153	10kg 125 235 327	
LGXS10-20	Wall installation (Unit: mm)	Vertical installation (Unit: mm)
Horizontal installation (Unit: mm)	A B C	A C
5kg 1218 844 493	5kg 464 778 1177	2kg 1602 1602
12kg 575 326 193	12kg 159 261 516	4kg 788 788
20kg 375 177 106	20kg 70 113 290	
LGXS10-10	Wall installation (Unit: mm)	Vertical installation (Unit: mm)
Horizontal installation (Unit: mm)	A B C	A C
10kg 1851 568 383	10kg 343 504 1784	3kg 1849 1849
20kg 973 263 177	20kg 136 199 885	5kg 1086 1086
30kg 671 162 109	30kg 67 98 552	8kg 656 656

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Payload - Acceleration / Deceleration Graph (Estimate)



Effective stroke and maximum speed during high acceleration or deceleration

Effective stroke	100	150	200	250	300	350	400	450	500	550	600	650
Maximum speed (mm/sec)	Lead 30	1800										
	Lead 20	1200										
	Lead 10	600										
	Lead 5	300										

Note. The bending unit cannot be used for the high agility mode.
 Note. The high agility mode is used in an effective stroke range of 100 to 650 (50 mm pitch).
 Note. There is no critical speed setting. The maximum speed can be set for a selectable stroke.
 The speed may not reach the maximum speed if the movement distance is short or depending on the operating conditions.
 Note. See P.124 for acceleration/deceleration and inertia moment.

Access the website below.



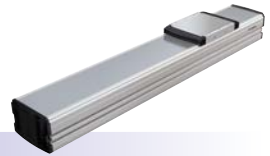
▶ The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS12

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS12

Model	Lead	Motor specification	Stroke
	30: 30 mm 20: 20 mm 10: 10 mm 5: 5 mm	No entry: Standard P: P specification (see below)	100 to 1250 (50 mm pitch)

[Caution]

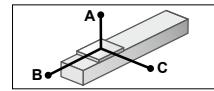
This system is provided as mechanical actuator unit and not including any adapters or electric components. Motor, driver and other components required for installation are the user's responsibility. Refer to user's manual for installation details. Refer to your motor manual for tuning or adjustment. Vibration or resonance from actuator will affect service life of actuator. The product performance may not be satisfied depending on the compatible motor. The bending unit cannot be used for the high agility mode.

Specifications

Applicable motor	400 W
Repeatability ^{Note 1}	+/-0.005 mm
Deceleration mechanism	Ground ball screw ϕ 15 (C5 class)
Stroke	100 mm to 1250 mm (50 mm pitch)
Maximum speed ^{Note 2} (or equivalent)	1800 mm/sec 1200 mm/sec 600 mm/sec 300 mm/sec
Ball screw lead	30 mm 20 mm 10 mm 5 mm
Maximum payload ^{Note 3} (or equivalent)	Horizontal 35 kg 50 kg 95 kg 115 kg Vertical 8 kg 15 kg 25 kg 45 kg
Rated thrust ^{Note 3} (or equivalent)	225 N 339 N 678 N 1360 N
Maximum dimensions of cross section of main unit	W 125 mm x H 101 mm
Overall length	ST + 211.5 mm
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent
Intake air ^{Note 5}	30 N ℓ /min to 90 N ℓ /min
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)

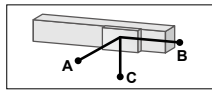
- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed.
 If the effective stroke exceeds 700 mm, the ball screw may resonate. (Critical speed)
 At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.126 for acceleration/deceleration and inertia moment.

Allowable overhang ^{Note}



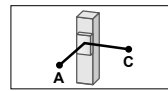
LGXS12-30

Horizontal installation (Unit: mm)			
	A	B	C
10kg	1796	1074	637
20kg	1300	531	332
35kg	1341	334	227



Wall installation (Unit: mm)

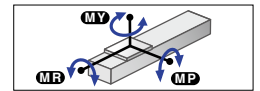
	A	B	C
10kg	631	1009	1720
20kg	316	466	1171
35kg	197	269	1130



Vertical installation (Unit: mm)

	A	C
3kg	2642	2642
6kg	1289	1289
8kg	951	951

Static loading moment



(Unit: N·m)		
MY	MP	MR
334	334	294

Adaptable Servo Motor

Specification	Flange size	<input type="checkbox"/> 60
	Wattage	400 W
Motor specification	Manufacturer	Model
	Yaskawa Electric Corp.	SGMJV-04 SGMJJ-04
	Keyence Corp.	SV- <input type="checkbox"/> 040 SV2- <input type="checkbox"/> 040
	Mitsubishi Electric Corp.	HF-KP43 HG-KR43 ^{Note 1} HK-KT43 ^{Note 1}
No entry	Omron Electronics	R88M-K40030 R88M-1M40030
	Panasonic Corp.	MSMD04 MSMS04 MHMF04
	Conversion adapter product model	Shim plate part number
GX-BEND-60 ^{Note 2}	KEV-M2295-00	

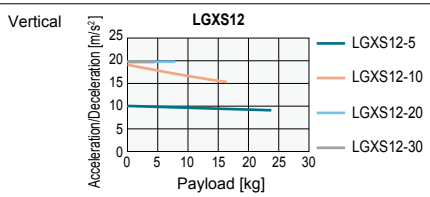
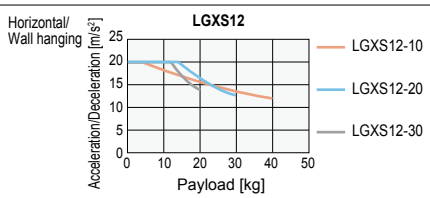
- Note 1. To combine with the conversion adapter <GX-BEND-60>, the shim plate (t1) is necessary.
 Note 2. For the specifications P, the bending unit cannot be used.

When used with high acceleration or deceleration (High agility mode)

Specifications

Stroke	100 mm to 650 mm (50 mm pitch)			
Ball screw lead	30 mm	20 mm	10 mm	5 mm
Maximum payload	20 kg	30 kg	40 kg	-
Maximum acceleration	Horizontal 19.62 m/s ² (2 G)	19.62 m/s ² (2 G)	19.62 m/s ² (2 G)	-
Maximum payload	4 kg	8 kg	16 kg	24 kg
Maximum acceleration	Vertical 19.62 m/s ² (2 G)	19.62 m/s ² (2 G)	19.62 m/s ² (2 G)	9.85 m/s ² (1 G)

Payload - Acceleration / Deceleration Graph (Estimate)



Allowable overhang ^{Note}

LGXS12-30

Horizontal installation (Unit: mm)			
	A	B	C
5kg	1216	1297	669
12kg	461	506	252
20kg	316	280	147

Wall installation (Unit: mm)

	A	B	C
5kg	648	1224	1183
12kg	226	436	427
20kg	117	213	266

Vertical installation (Unit: mm)

	A	C
2kg	1984	1984
4kg	960	960

LGXS12-5

Vertical installation (Unit: mm)		
	A	C
8kg	1487	1487
16kg	712	712
24kg	454	454

LGXS12-20

Horizontal installation (Unit: mm)			
	A	B	C
10kg	999	807	489
20kg	521	378	231
30kg	382	234	146

Wall installation (Unit: mm)

	A	B	C
10kg	458	740	966
20kg	196	311	479
30kg	109	168	325

Vertical installation (Unit: mm)

	A	C
3kg	2031	2031
5kg	1193	1193
8kg	722	722

LGXS12-10

Horizontal installation (Unit: mm)			
	A	B	C
15kg	1668	737	535
25kg	1060	423	308
40kg	709	246	180

Wall installation (Unit: mm)

	A	B	C
15kg	491	672	1628
25kg	263	358	1012
40kg	134	181	644

Vertical installation (Unit: mm)

	A	C
5kg	2071	2071
10kg	1011	1011
16kg	612	612

- Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Effective stroke and maximum speed during high acceleration or deceleration

Maximum speed (mm/sec)	Effective stroke										
	100	150	200	250	300	350	400	450	500	550	600
Lead 30	1800										
	1200										
	600										
	300										

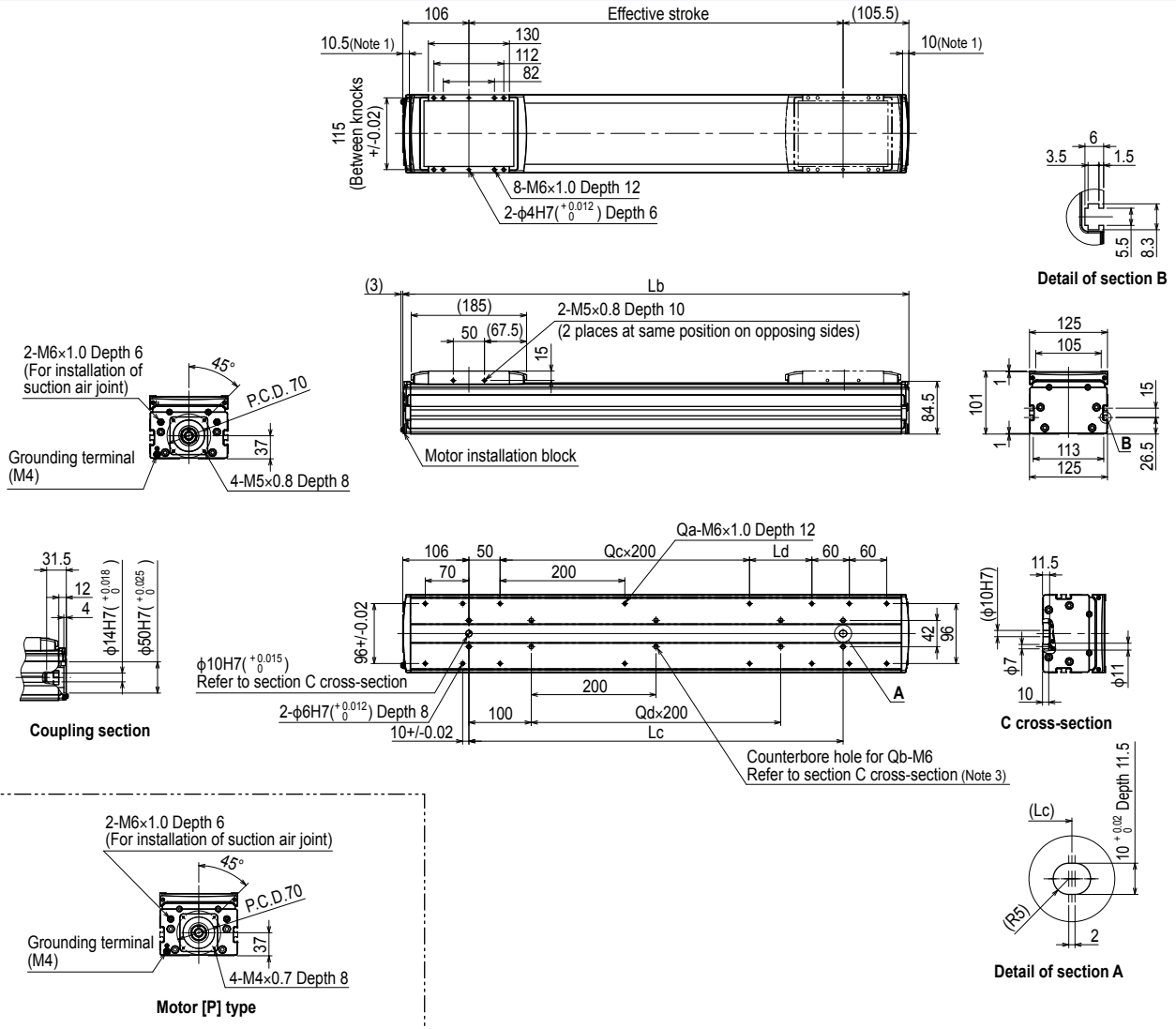
- Note. The bending unit cannot be used for the high agility mode.
 Note. The high agility mode is used in an effective stroke range of 100 to 650 (50 mm pitch).
 Note. There is no critical speed setting. The maximum speed can be set for a selectable stroke.
 The speed may not reach the maximum speed if the movement distance is short or depending on the operating conditions.
 Note. See P.128 for acceleration/deceleration and inertia moment.

Access the website below.



► The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS12



- Note 1. Stop positions are determined by the mechanical stoppers at both ends.
- Note 2. The length under head of the hex socket head bolts <M6 × 1.0> used to mount the body with the mounting counterbore holes (section C cross-section) must be <<20 mm or more>>. The recommended length under head of the hex socket head bolts <M6 × 1.0> used to mount the body with the mounting tap hole specifications is <<frame thickness + 10 mm or less>>.
- Note 3. When using the mounting counterbore holes (section C cross-section) to mount the body, remove the seal, and then fix.
- Note 4. Grease gun nozzle (recommended) (see P.143 for detail)

Effective stroke	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250		
Lb	311.5	361.5	411.5	461.5	511.5	561.5	611.5	661.5	711.5	761.5	811.5	861.5	911.5	961.5	1011.5	1061.5	1111.5	1161.5	1211.5	1261.5	1311.5	1361.5	1411.5	1461.5		
Lc	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250		
Ld	0	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150		
Qa	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	16	18	18	18	20	20	20		
Qb	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16		
Qc	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5		
Qd	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5		
Weight (kg)	6.5	7.1	7.8	8.5	9.1	9.8	10.5	11.2	11.8	12.5	13.2	13.9	14.5	15.2	15.9	16.5	17.2	17.9	18.6	19.2	19.9	20.6	21.3	21.9		
Maximum speed (mm/sec)	Lead 30	1800											1530	1350	1170	990	900	810	720	630	540	450				
	Lead 20	1200											1020	900	780	660	600	540	480	420	360	300				
	Lead 10	600											510	450	390	330	300	270	240	210	180	150				
	Lead 5	300											255	225	195	165	150	135	120	105	90	75				
Speed setting	-											85%	75%	65%	55%	50%	45%	40%	35%	30%	25%					

Features

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Acceleration/Deceleration Inertia Moment

Option

Single axis robot positioner

LGXS16

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS16

Model	Lead	Motor specification	Stroke
	40: 40 mm 20: 20 mm 10: 10 mm	No entry: Standard P: P specification (see below)	100 to 1450 (50 mm pitch)

[Caution]

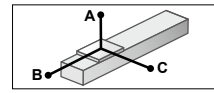
This system is provided as mechanical actuator unit and not including any adapters or electric components. Motor, driver and other components required for installation are the user's responsibility. Refer to user's manual for installation details. Refer to your motor manual for tuning or adjustment. Vibration or resonance from actuator will affect service life of actuator. The product performance may not be satisfied depending on the compatible motor. The bending unit cannot be used for the high agility mode.

Specifications

Applicable motor	750 W		
Repeatability ^{Note 1}	+/-0.005 mm		
Deceleration mechanism	Ground ball screw ϕ 20 (C5 class)		
Stroke	100 mm to 1450 mm (50 mm pitch)		
Maximum speed (or equivalent) ^{Note 2}	2400 mm/sec	1200 mm/sec	600 mm/sec
Ball screw lead	40 mm	20 mm	10 mm
Maximum payload (or equivalent) ^{Note 3}	Horizontal	45 kg	95 kg
	Vertical	12 kg	28 kg
Rated thrust (or equivalent) ^{Note 3}	320 N	640 N	1280 N
Maximum dimensions of cross section of main unit	W 160 mm x H 130 mm		
Overall length	ST + 242.5 mm		
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent		
Intake air ^{Note 5}	30 N ℓ /min to 90 N ℓ /min		
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)		

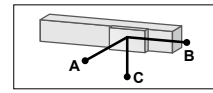
- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed. If the effective stroke exceeds 800 mm, the ball screw may resonate. (Critical speed)
 At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.130 for acceleration/deceleration and inertia moment.

Allowable overhang ^{Note}

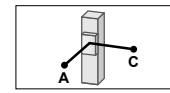


LGXS16-40

Horizontal installation (Unit: mm)	A	B	C
15kg	2876	1866	1253
30kg	2385	997	776
45kg	2339	720	604

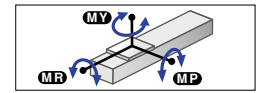


Wall installation (Unit: mm)	A	B	C
15kg	1273	1802	2797
30kg	782	935	2263
45kg	598	658	2174



Vertical installation (Unit: mm)	A	C
3kg	6605	6605
6kg	3699	3699
12kg	2827	2827

Static loading moment



(Unit: N·m)		
MY	MP	MR
706	706	620

Adaptable Servo Motor

Specification	Flange size	<input type="checkbox"/> 80	
	Wattage	750 W	
Motor specification	Manufacturer	Model	
	No entry	Yaskawa Electric Corp.	SGMJV-08 SGMJJ-08
		Keyence Corp.	SV- <input type="checkbox"/> 075 SV2- <input type="checkbox"/> 075
	P	Mitsubishi Electric Corp.	SF-KP73 HG-KR73 ^{Note 1} HK-KT7M3 ^{Note 1}
Omron Electronics		R88M-K75030 R88M-1M75030	
Conversion adapter product model	Shim plate part number	MSMD08	
		MSMF08	
GX-BEND-80 ^{Note 2}	KEX-M2295-00		

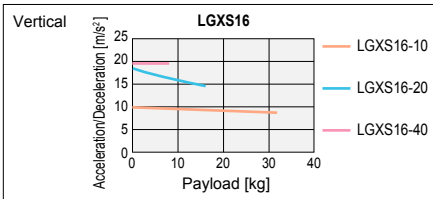
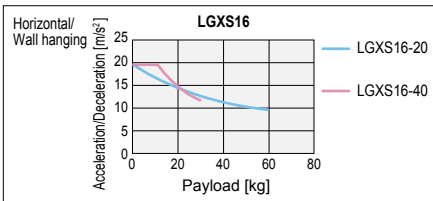
- Note 1. To combine with the conversion adapter <GX-BEND-80>, the shim plate (t1) is necessary.
 Note 2. For the specifications P, the bending unit cannot be used.

When used with high acceleration or deceleration (High agility mode)

Specifications

Stroke	100 mm to 800 mm (50 mm pitch)		
Ball screw lead	40 mm	20 mm	10 mm
Maximum payload	Horizontal	30 kg	60 kg
	Vertical	-	-
Maximum acceleration	Horizontal	19.62 m/s ² (2 G)	19.84 m/s ² (2 G)
	Vertical	-	-
Maximum payload	Horizontal	8 kg	16 kg
	Vertical	32 kg	-
Maximum acceleration	Horizontal	19.62 m/s ² (2 G)	18.43 m/s ² (1.9 G)
	Vertical	-	11.17 m/s ² (1.1 G)

Payload - Acceleration / Deceleration Graph (Estimate)



Allowable overhang ^{Note}

LGXS16-40

Horizontal installation (Unit: mm)	A	B	C
10kg	1271	1669	836
20kg	725	803	429
30kg	534	514	287

Wall installation (Unit: mm)	A	B	C
10kg	816	1585	1240
20kg	404	725	683
30kg	259	441	480

Vertical installation (Unit: mm)	A	C
3kg	2904	2904
5kg	1710	1710
8kg	1038	1038

LGXS16-10

Vertical installation (Unit: mm)	A	C
10kg	2951	2951
20kg	1438	1438
32kg	870	870

LGXS16-20

Horizontal installation (Unit: mm)	A	B	C
20kg	1722	1123	875
40kg	952	535	428
60kg	682	339	276

Wall installation (Unit: mm)	A	B	C
20kg	842	1056	1679
40kg	388	470	895
60kg	232	275	611

Vertical installation (Unit: mm)	A	C
5kg	3473	3473
10kg	1723	1723
16kg	1064	1064

- Note. Distance from center of slider top to center of gravity of object being carried at guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Effective stroke and maximum speed during high acceleration or deceleration

Maximum speed (mm/sec)	Effective stroke	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
		Lead 40	2400													
Lead 20	Lead 10	1200														
		600														

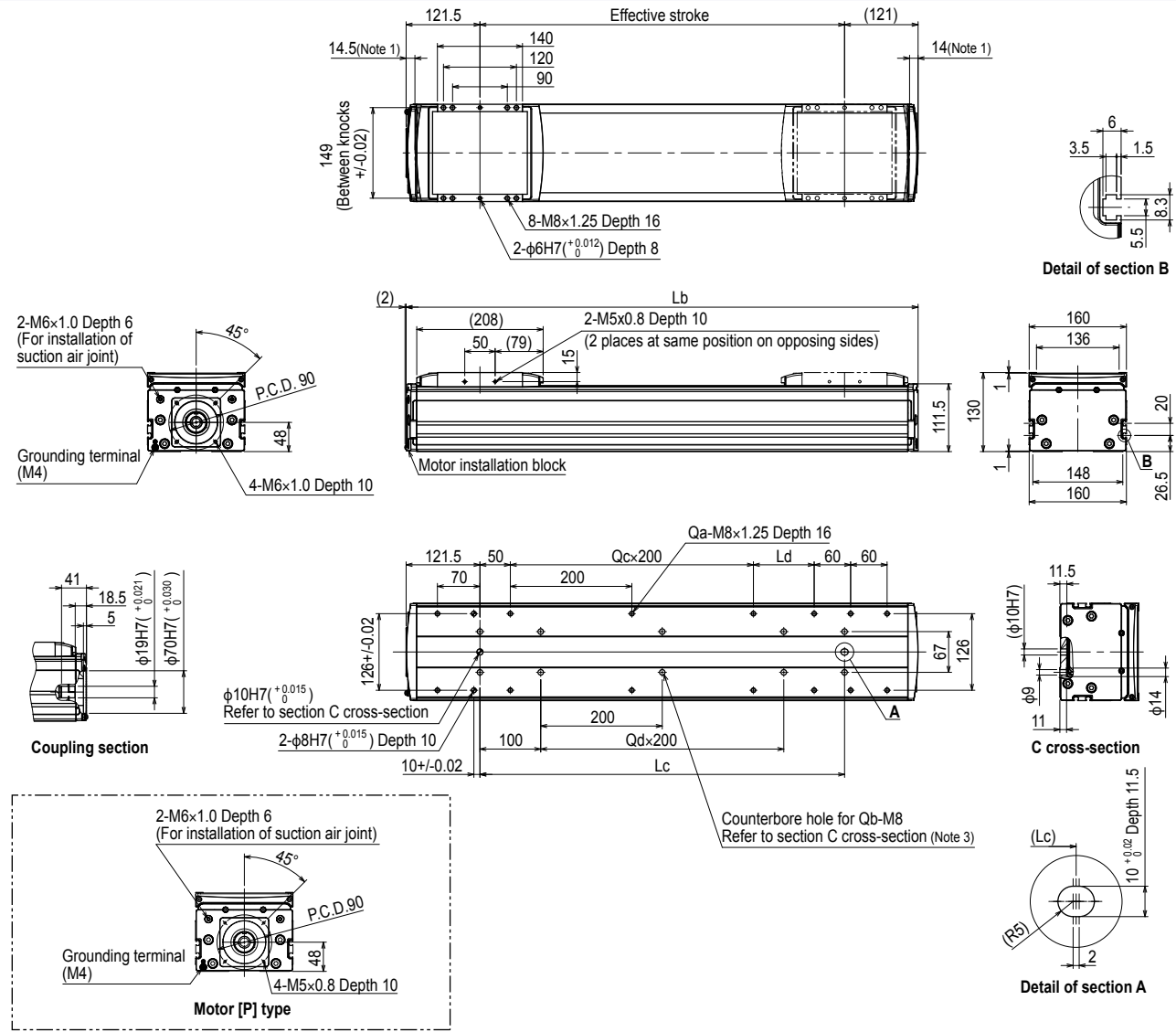
- Note. The bending unit cannot be used for the high agility mode.
 Note. The high agility mode is used in an effective stroke range of 100 to 800 (50 mm pitch).
 Note. There is no critical speed setting. The maximum speed can be set for a selectable stroke.
 The speed may not reach the maximum speed if the movement distance is short or depending on the operating conditions.
 Note. See P.132 for acceleration/deceleration and inertia moment.

Access the website below.



▶ The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS16



- Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The length under head of the hex socket head bolts <M8 x 1.25> used to mount the body with the mounting counterbore holes (section C cross-section) must be <<25 mm or more>>.
 The recommended length under head of the hex socket head bolts <M8 x 1.25> used to mount the body with the mounting tap hole specifications is <<frame thickness + 15 mm or less>>.
 Note 3. When using the mounting counterbore holes (section C cross-section) to mount the body, remove the seal, and then fix.
 Note 4. Grease gun nozzle (recommended) (see P.143 for detail)

Effective stroke	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450										
Lb	342.5	392.5	442.5	492.5	542.5	592.5	642.5	692.5	742.5	792.5	842.5	892.5	942.5	992.5	1042.5	1092.5	1142.5	1192.5	1242.5	1292.5	1342.5	1392.5	1442.5	1492.5	1542.5	1592.5	1642.5	1692.5										
Lc	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450										
Ld	0	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150										
Qa	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20	20	20	22	22	22										
Qb	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18										
Qc	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6										
Qd	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6										
Weight (kg)	11.7	12.7	13.7	14.7	15.7	16.6	17.6	18.6	19.6	20.6	21.5	22.5	23.5	24.5	25.5	26.5	27.4	28.4	29.4	30.4	31.4	32.4	33.3	34.3	35.3	36.3	37.3	38.2										
Maximum speed (mm/sec)	Lead 40																2400																					
	Lead 20																1200																					
	Lead 10																600																					
	Speed setting																-																					
																	2160	1920	1680	1440	1320	1200	1080	960	840	720	600											
																	1080	960	840	720	660	600	540	480	420	360	300											
																	540	480	420	360	330	300	270	240	210	180	150											
																	90%	80%	70%	60%	55%	50%	45%	40%	35%	30%	25%											

Features

Basic model

Advanced model

Basic model

Basic model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Acceleration/Deceleration Inertia Moment

Option

Single axis robot positioner

EP-01

LGXS20

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS20

Model	Lead	Motor specification	Stroke
	40: 40 mm 20: 20 mm 10: 10 mm	No entry: Standard P: P specification (see below)	100 to 1450 (50 mm pitch)

[Caution]

This system is provided as mechanical actuator unit and not including any adapters or electric components.

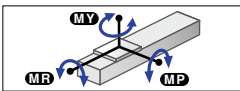
Motor, driver and other components required for installation are the user's responsibility. Refer to user's manual for installation details. Refer to your motor manual for tuning or adjustment. Vibration or resonance from actuator will affect service life of actuator. The product performance may not be satisfied depending on the compatible motor.

Specifications

Applicable motor	750 W		
Repeatability ^{Note 1}	+/- 0.005 mm		
Deceleration mechanism	Ground ball screw φ 20 (C5 class)		
Stroke	100 mm to 1450 mm (50 mm pitch)		
Maximum speed ^{Note 2} (or equivalent)	2400 mm/sec	1200 mm/sec	600 mm/sec
	40 mm	20 mm	10 mm
	Ball screw lead		
Maximum payload ^{Note 3} (or equivalent)	Horizontal	65 kg	130 kg
	Vertical	15 kg	35 kg
Rated thrust ^{Note 3} (or equivalent)	320 N	640 N	1280 N
	Maximum dimensions of cross section of main unit		
	W 200 mm × H 140 mm		
Overall length	ST + 288.5 mm		
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent		
Intake air ^{Note 5}	30 Nℓ/min to 90 Nℓ/min		
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)		

- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed.
 If the effective stroke exceeds 800 mm, the ball screw may resonate. (Critical speed)
 At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.133 for acceleration/deceleration and inertia moment.

Static loading moment

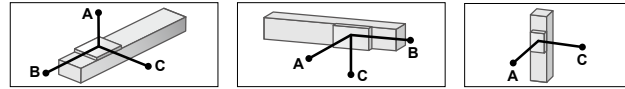


	(Unit: N·m)		
	MY	MP	MR
	1423	1423	1251

Adaptable Servo Motor

Specification	Flange size	<input type="checkbox"/> 80
	Wattage	750 W
Motor specification	Manufacturer	Model
	No entry	Yaskawa Electric Corp.
Keyence Corp.		SV- <input type="checkbox"/> 075 SV2- <input type="checkbox"/> 075
Mitsubishi Electric Corp.		HF-KP73
		HG-KR73 ^{Note 1} HK-KT7M3 ^{Note 1}
P	Omron Electronics	R88M-K75030 R88M-1M75030
		MSMD08 MSMF08 MHMF08
	Panasonic Corp.	

Allowable overhang ^{Note}



LGXS20-40	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)			Vertical installation (Unit: mm)				
		A	B	C		A	B	C		A	C
	20kg	5318	2821	2096	20kg	2171	2751	5211	5kg	8187	8187
	40kg	4836	1609	1369	40kg	1417	1539	4667	10kg	5203	5203
65kg	4824	1088	1001	65kg	1013	1018	4575	15kg	4810	4810	

LGXS20-20	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)			Vertical installation (Unit: mm)				
		A	B	C		A	B	C		A	C
	50kg	5436	1493	1377	50kg	1390	1423	5265	20kg	3436	3436
	80kg	4417	911	854	80kg	849	841	4153	30kg	2600	2600
	100kg	4592	756	727	100kg	708	686	4253	35kg	3073	3073
130kg	4338	596	584	130kg	550	526	3933				

LGXS20-10	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)			Vertical installation (Unit: mm)				
		A	B	C		A	B	C		A	C
	40kg	22519	2607	2713	40kg	2704	2537	22210	20kg	5157	5157
	80kg	16716	1274	1331	80kg	1293	1204	16141	40kg	2553	2553
	120kg	14066	830	868	120kg	818	760	13223	65kg	1600	1600
160kg	12284	608	637	160kg	580	538	11190				

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Conversion adapter product model	Shim plate part number
GX-BEND-80 ^{Note 2}	KEX-M2295-00

Note 1. To combine with the conversion adapter <GX-BEND-80>, the shim plate (t1) is necessary.

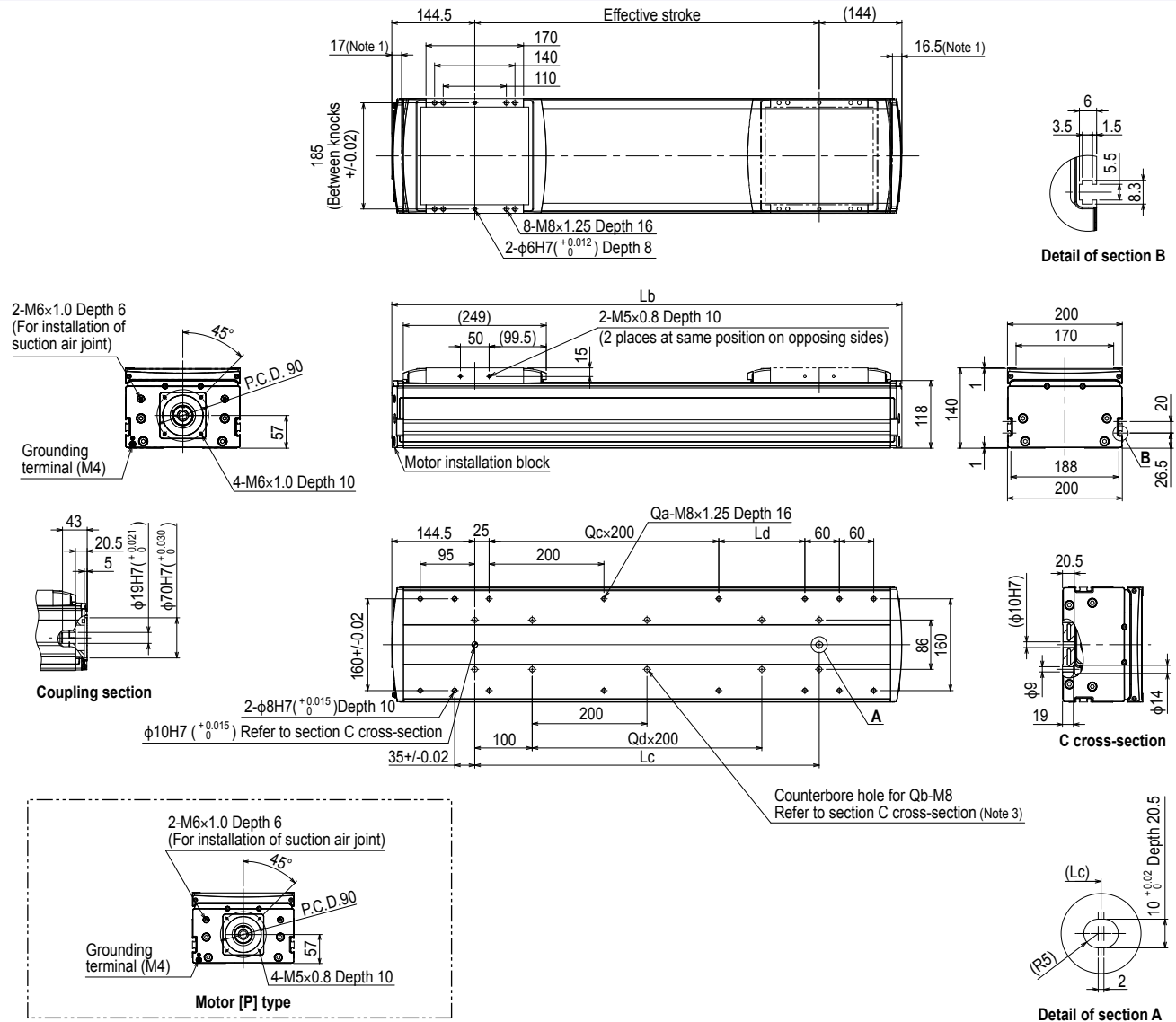
Note 2. For the specifications P, the bending unit cannot be used.

Access the website below.



▶ The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS20



- Note 1. Stop positions are determined by the mechanical stoppers at both ends.
- Note 2. The length under head of the hex socket head bolts <M8 × 1.25> used to mount the body with the mounting counterbore holes (section C cross-section) must be <<25 mm or more>>.
- The recommended length under head of the hex socket head bolts <M8 × 1.25> used to mount the body with the mounting tap hole specifications is <<frame thickness + 15 mm or less>>.
- Note 3. When using the mounting counterbore holes (section C cross-section) to mount the body, remove the seal, and then fix.
- Note 4. Grease gun nozzle (recommended) (see P.143 for detail)

Effective stroke	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450
Lb	388.5	438.5	488.5	538.5	588.5	638.5	688.5	738.5	788.5	838.5	888.5	938.5	988.5	1038.5	1088.5	1138.5	1188.5	1238.5	1288.5	1338.5	1388.5	1438.5	1488.5	1538.5	1588.5	1638.5	1688.5	1738.5
Lc	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450
Ld	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200
Qa	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	18	18	18	18	20	20	20	20	20	22	22	22	22
Qb	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18
Qc	0	0	0	0	1	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6
Qd	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6
Weight (kg)	17.2	18.5	19.8	21.1	22.4	23.7	25.0	26.3	27.6	28.8	30.1	31.4	32.7	34.0	35.3	36.6	37.9	39.2	40.4	41.7	43.0	44.3	45.6	46.9	48.2	49.5	50.8	52.0
Maximum speed (mm/sec)	Lead 40																2160	1920	1680	1440	1320	1200	1080	960	840	720	600	
	Lead 20																1080	960	840	720	660	600	540	480	420	360	300	
	Lead 10																540	480	420	360	330	300	270	240	210	180	150	
	Speed setting																90%	80%	70%	60%	55%	50%	45%	40%	35%	30%	25%	

Features

Basic model

Advanced model

Motor type

Red type

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Acceleration/Deceleration

Inertia Moment

Option

Single axis force positioner

EP-01